IPMV51734

Problems and Cures

Special acknowledgements to D. Kramer

Working Principle



Installation LSS5 Inner Detector



Problems encountered and cured during sdh 2003:

- Installation delayed due to supply problems (MCP, vacuum flange). Commissioning August 2002.
- Evidence for e-cloud:
 - DC voltage level increases after third injection when signal of electrode directly observed on a scope.
 - A test showed that electron emission current from heating wire decreases after third injection.
 - Video signal increases after third injection.
- Severe instabilities of HV power supplies due to electron cloud and RF with LHC type beam:
 - Application of NEG (Non Evaporable Getter, TiZrV: 15/34/51%) layer on electrodes: low SEY.
 - RF absorbers near HV PS and HV series resistors near detector.
- Beam related EMI on TV screen:
 - Cover plate for view port.
 - Repaired loose ground contact within video driver module.
 - Repaired interruption in video cable screen.
 - TV replaced by base band video B&W monitor.

Problems encountered and cured in course 2003.

- Bad electrical contacts of phosphor screen after bake-out (200°C) of NEG:
 - Insertion of thin CuBe frame with flexible contacts for phosphor.
- Damage to central region of MCP due to high output signal:
 - Decrease of MCP gain compensated by image intensifier. Decrease MCP output current, increase of life time.
- Lighting up of phosphor screen with short LHC bunches at high energy (Even without HV applied!):
 - Removal of HV series resistances.
- Limited image resolution:
 - Closed diaphragm of camera lens by 50%.
- Tilt on video image due to stray B-field:
 - Addition of µ-metal screen, decreasing influence Bfield on image intensifier.
 - Reduction of magnet current by 50%.







Observations in 2003 1/2



- Pilot bunch has been observed using intensified camera.
- Analysis of fixed pattern noise shows possibility of improving signal quality by subtraction, especially beneficial at low energy.
- At high energy, 50% too large sigma's were measured with bunch pilot (very small size): resolution limitation.

14/1/2004

Observations in 2003 2/2



- Decreasing intensity until 2-nd injection:
 - Dropping vacuum pressure after vanishing e-cloud of previous cycle?
- Rising intensity after third injection:
 - Rising vacuum pressure due to electron cloud build-up?
 - Detected cloud electrons adding to useful signal?
- MCP saturation after acceleration:
 - Higher peak values due to beam size shrinking.

Remaining Problems and Cures in shd 2004 (1/2)

- Damaged MCP:
 - Replacement with new one operated at lower gain and relayed by LLL camera.
 - Suppression of 2-nd MCP in order to operate first one with higher voltage.
- Low phosphor gain leading to overexposure of MCP:
 - Phosphor change from CdS:In to $Y_3AI_5O_{12}$:Ce (P46) to increase sensitivity and decrease gain on MCP. Scarify high speed single bunch measurement.
- Heating wire does not procure sufficiently homogeneous signal for calibration purposes:
 - Removal of heating wire.
- Suppression of electron cloud in active region of detector.
 - NEG coating on MCP input and grid wires.
- Resolution limitation due to insufficient video bandwidth?
 - New video driver.
 - Turn camera by 90°?
- Contribution to tails of beam profile by secondary electrons from wire grid on cathode:
 - Decrease of number of wires on cathode grid to decrease contribution to tails.

Remaining Problems and Cures in shd 2004 (2/2)

- Non homogeneous light distribution in transverse direction due to non total internal reflection in prism:
 - Application of reflective AI coating on prism for total internal reflection to improve light distribution. (See drawing)
- Non homogeneous light distribution in longitudinal direction not yet understood, but probably no influence on profile measurement.
- Internal optical reflections:
 - Treatment of relevant surfaces to absorb and/or scatter parasitic reflections.
- Bright spot on phosphor (outside active region) depending on applied voltage and magnetic field :
 - Cleaning of MCP mounting parts.
- Still sometimes lighting up of phosphor in very special conditions (only once observed in 2003, believed to be due to RF):
 - Addition of external RF absorbers on the HV feed-throughs on the detector.



New Hardware

- Low Light Level camera:
 - Lower noise.
 - Higher resolution.
 - Insensitive to B-field.
 - Life-time insensitive to over exposure.
- 32 channel miniature photo multiplier tube:
 - High speed turn/turn measurement for injection studies.
- Dedicated optics:
 - Splitter.
 - Higher aperture.
- Video drivers:
 - Less EMI sensitivity, better signal quality.
 - More bandwidth, higher resolution.









Software Upgrades:

- Ongoing:
 - IPM HV control with programmable dynamic gain BGIPFG:
 - Optimise dynamic behaviour for constant output current.
 - Avoid MCP saturation and damage at high beam energy.
 - Improve S/N ratio at low beam energy.
- Wish list:
 - Repair pending bugs in Biscoto BTVSPS:
 - Main problem: timing drift.
 - Some ergonomic issues.
 - Tilt correction:
 - Improve accuracy beam size measurement.
 - Fixed pattern noise measurement and subtraction:
 - Improve signal quality.
 - Control on/off/gain LLL camera.

Tests and measurements 2004:

- Test of effectiveness of modifications intended to be improvements.
- Correlation between pressure and signal decrease after first injection.
- Investigate remaining resolution limits (optics, B-field, video bandwidth/offset, image tilt).
- Calibration campaign of upgraded equipment with BWS with different type of beams.
- Compare results between FT and LHC beam:
 - Bunch shortening effects.
 - E-cloud effects.
- Investigate remaining unexplained behavior:
 - Gradual beam blow-up (~10%) at low energy and high intensity.
 - Gain instabilities of MCP.
 - HV jumps not in accordance with DAC values.
 - Cathode HV sometimes does not follow DAC values.
 - Non symmetry in magnet currents.

Future plans

- If necessary, build and test new idea of MCP calibration wire grid.
- If time available, upgrade HV control card.
- If possible, unify into one application all bits and pieces of software actually needed to control the instrument:
 - Camera control.
 - IPM HV control.
 - BTV data acquisition.
 - Magnet control.
- Build new horizontal IPM for 2006.
- Build 4 new IPMs for LHC for 2007.